

Discriminants of Brauer Algebra

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Abstract: In this work we study how to compute the brauer algebra discriminant and also define a matrix $Z_{m,k}(x)$.

INTRODUCTION:

In the beginning of 20th century invariant theorists began to study the commuting algebras of the tensor powers of defining representations for the classical groups $G = \text{Gl}(n, \mathbb{C}), \text{Sl}(n, \mathbb{C}), \text{O}(n, \mathbb{C}), \text{So}(n, \mathbb{C})$ and $\text{Sp}(2m, \mathbb{C})$.

These algebras may be defined as follows. Let G be a classical group. Let V be its defining representation, and let $T^f V$ be the f^{th} tensor power of V . (i.e.,) $T^f V = V_1 \otimes V_2 \otimes \dots \otimes V_f$. The group action of G on V lifts to the diagonal action of G on $T^f V$ defined by $g.(V_1 \otimes V_2 \otimes \dots \otimes V_f) = (gV_1) \otimes (gV_2) \otimes \dots \otimes (gV_f)$. Define the commuting algebra $\text{End}_G(T^f V)$ of this action to be the algebra of all linear transformations of $T^f V$ which commute with this action of G . In the case of $G = \text{Gl}(n, \mathbb{C})$ Schur showed that there is a surjective algebra homomorphism from CS_f onto $\text{End}_{\text{Gl}(n, \mathbb{C})}(T^f \mathbb{C}^n)$, which is an isomorphism for $f \leq n$. The kernel of this homomorphism, gives a complete explanation of the centralizer algebra $\text{End}_{\text{Gl}(n, \mathbb{C})}(T^f \mathbb{C}^n)$.

In 1937, when $G = \text{O}(n, \mathbb{C})$ and $\text{Sp}(2m, \mathbb{C})$ Richard Brauer defined two algebras $A_f^{(x)}$ and $B_f^{(x)}$ where ' f ' is a positive integer and ' x ' is a real indeterminate. The surjective algebra homomorphism for the algebras $A_f^{(x)}$ and $B_f^{(x)}$ are constructed as follows:-

$$\phi_f^{(n)}: A_f^{(n)} \longrightarrow \text{End}_{\text{O}(n, \mathbb{R})}(T^f \mathbb{R}^n)$$

$$\chi_f^{(2m)}: B_f^{(2m)} \longrightarrow \text{End}_{\text{sp}(2m, \mathbb{R})}(T^f \mathbb{R}^{2m})$$

If n and m are large enough then these homomorphisms are isomorphisms. When these homomorphisms are not an isomorphism then Richard Brauer failed to give the explanation of the kernel of the maps. In order to give a clear explanation of these kernels, Phil Hanlon and David Wales began to study the structure of the algebras $A_f^{(x)}$ and $B_f^{(x)}$ where ' x ' is an arbitrary real. The algebras $A_f^{(x)}$ and $B_f^{(-x)}$ are isomorphic to each other. So it was only necessary to study the algebra $A_f^{(x)}$.

The authors were able to describe the radicals of $A_f^{(x)}$ and the matrix ring decomposition of $A_f^{(x)} / \text{Rad}(A_f^{(x)})$. Later this problem was reduced to the problem of computing the ranks of certain combinatorially defined matrices $Z_{m,k}(x)$.

1. Defining the matrix $Z_{m,k}(x)$:

The computational problem will be to compute the rank of certain combinatorially defined matrices $Z_{m,k}(x)$ for every complex number x . The determinant of $Z_{m,k}(x)$ is known to be nonzero as a polynomial in x . So the rank of $Z_{m,k}(x)$ is completely determined except at a finite number of values of x . The finite values of x are those x that are the

roots of $\det(Z_{m,k}(x))$. So the computational problem breaks into two parts:-

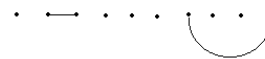
1. Compute the roots of $\det(Z_{m,k}(x))$.
2. For each root r , compute the rank of $Z_{m,k}(r)$

1.1. Definition:

Let m and k be nonnegative integers. An (m, k) partial 1-factor is a graph with $m+2k$ points and k lines which satisfies:-

1. Every point has degree 0 or 1.
2. The m points of degree 0 are labeled with the numbers $1, 2, \dots, m$.

For example,



is a $(6, 2)$ factor.

1.2. Notation:

Here we use ' f ' to denote $m+2k$, and lower case Greek letters $\delta, \delta_1, \delta_2, \dots$ to denote partial 1-factors. $B_{m,k}$ denote the set of all (m, k) partial 1-factors. Let $V_{m,k}$ be the complex vector space with basis $B_{m,k}$. The points of degree '0' in a partial 1-factor δ are called the free points of δ .

1.3. Definition:

Let δ_1 and δ_2 be elements of $B_{m,k}$. The union of δ_1 and δ_2 is a graph consisting of some number $\gamma(\delta_1, \delta_2)$ of cycles together with m paths P_1, \dots, P_m . If u is an endpoint of P_i , then u is a free point of either δ_1 or δ_2 . Hence, the end points of each path are labeled. We say δ_1 and δ_2 are consistent if each path of $\delta_1 \cup \delta_2$ has the property that its endpoints have the same label. Otherwise, δ_1 and δ_2 are inconsistent.

1.4. Definition:

Let m and k be nonnegative integers. Define a matrix $Z_{m,k}(x)$ with rows and columns indexed by $B_{m,k}$. For $\delta_1, \delta_2 \in B_{m,k}$ let the $(\delta_1, \delta_2)^{\text{th}}$ entry of $Z_{m,k}(x)$ be defined by

$$Z_{m,k}(x)_{\delta_1, \delta_2} \begin{cases} = x^{\gamma(\delta_1, \delta_2)} & \text{if } \delta_1 \text{ and } \delta_2 \text{ are,} \\ 0 & \text{if } \delta_1 \text{ and } \delta_2 \text{ are} \\ & \text{inconsistent.} \end{cases}$$

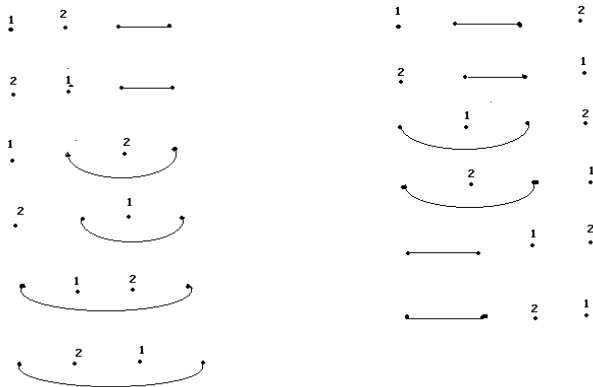
1.5. Note:

Each diagonal entry of $Z_{m,k}(x)$ is x^k and that every off-diagonal entry is either 0 or x^e with $e < k$. So the determinant of $Z_{m,k}(x)$ is a nonzero polynomial in x of degree $|B_{m,k}|$.

1.6. Example:

Let $f=4$ and $m=2$. In this case, the matrix $Z_{m,k}(x)$ is 12×12 .

An ordered basis for $B_{m,k}$ is given below:



Thus, the matrix $Z_{m,k}(x)$ with respect to this is given by

$$Z_{2,1}(x) = \begin{pmatrix} x & 0 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & x & 0 & 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & x & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & x & 0 & 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & x & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 & x & 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & x & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & x & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 & x & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & x & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 & 0 & 1 & 0 & x & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 & x \end{pmatrix}$$

The size of $B_{m,k}$ is $|B_{m,k}| = (m+2k)! / 2^k k!$
 Here $m=2, k=1$.
 for the above the size of $B_{m,k}$ is $(2+2*1)! / 2^1 1! = 4! / 2 = 4*3/2 = 6$

1.7. Theorem:

Let G be a finite group with irreducible representation Φ_1, \dots, Φ_c . Let Φ be a representation of G on a complex vector space V which decomposes into irreducible as $\Phi = \sum m_i \Phi_i$; $i: 1$ to c

Let Z be a linear transformation of V which commutes with the action of G . Then Z is similar to a matrix which is a direct sum over i of matrices Z_i , where Z_i is a $m_i \times m_i$ matrix repeated in the direct sum $\text{deg}(\Phi_i)$ times. Moreover, Z_i can be computed as follows:

Step 1: Choose a complete set of Primitive orthogonal idempotent

$e_v^{(u)} : 1 \leq u \leq c, 1 \leq v \leq \text{deg}(\Phi_u)$ in the group algebra CG .

Step 2: Find m_i vectors $v_1 \dots v_{m_i} \in V$ such that $\Phi(e_i^{(j)}) v_{mi}$ are linearly independent.

Step 3:-

Let $v_1^{(i)}$ be the subspace of V spanned by $\Phi(e_1^{(i)}) v_1 \dots \Phi(e_1^{(i)}) v_{m_i}$. The space $v_1^{(i)}$ is Z -invariant and Z_i is the restriction of Z to $v_1^{(i)}$.

2. COMPUTING THE BRAUER ALGEBRA DISCRIMINANTS

2.1. Lemma:

Let μ and λ be partitions of m and f , respectively, and let $m(\mu, \lambda)$ denote the multiplicity of $\Phi_\lambda \otimes \Phi_\mu$ in $V_{m,k}$. Then

$$m(\mu, \lambda) = \sum_{\substack{\eta \vdash 2k \\ \eta \text{ even}}} g_{\lambda\mu\eta}$$

Proof:

Let G be $S_f \times S_m$

Let H be the subgroup $(S_{2k} \times S_m) \times S_m$, and let S be the subgroup of H given by

$$S = (\pi, \sigma, \sigma) : \pi \in B_{2k}, \sigma \in \text{Sym}(m)$$

Here, B_{2k} denotes the hyperoctahedral group of $k \times k$ signed permutation matrices, which is considered to be a subgroup of S_{2k} .

G acts as a transitive permutation group on the set $B_{m,k}$. So the action of G on $V_{m,k}$ is the induction of the trivial character ϵ from the stabilizer of any $\Delta_0 \in B_{m,k}$ to G

Choose

We have the stabilizer of Δ_0 is S .

Using a theorem of Littlewood and some well-known facts

$$\Delta_0 = \begin{matrix} \longrightarrow & \cdot & \cdot & \cdot & \longrightarrow & \cdot & \cdot & \cdot \end{matrix}$$

about the structure of group algebras, we have,

$$\text{ind}_S^H(\epsilon) = \bigoplus_{\substack{\eta \vdash 2k \\ \eta \text{ even}}} \bigoplus_{\mu \vdash m} \varphi_\eta \otimes \varphi_\mu \otimes \varphi_\mu$$

By the Littlewood – Richardson rule we have for each η, μ .

$$\text{ind}_H^G(\varphi_\eta \otimes \varphi_\mu \otimes \varphi_\mu) = \sum_{\lambda \vdash f} g_{\lambda\mu\eta} \varphi_\lambda \otimes \varphi_\mu$$

Hence the theorem is proved.

Now, fix partitions $\mu \vdash m$ and $\lambda \vdash f$. If μ is not contained in λ , then $g_{\lambda\mu\eta} = 0$ for all η ,

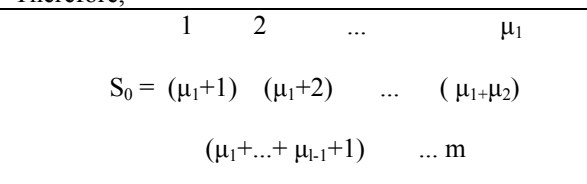
$$\text{So } m(\mu, \lambda) = 0.$$

Therefore, we may assume that $\mu \subseteq \lambda$.

For that, we will have to identify a particular idempotent ‘ e ’ in the group algebra of G corresponding to the irreducible representation $\varphi_\lambda \otimes \varphi_\mu$.

To obtain the idempotent ‘ e ’, first let S_0 be the minimal standard young tableau of shape μ .

Therefore,



Next, let t_0 be the standard young tableau of shape λ which agrees with S_0 on the intersection of λ and μ and which has the minimal filling of $[\lambda/\mu]$ with $m+1, \dots, f$.

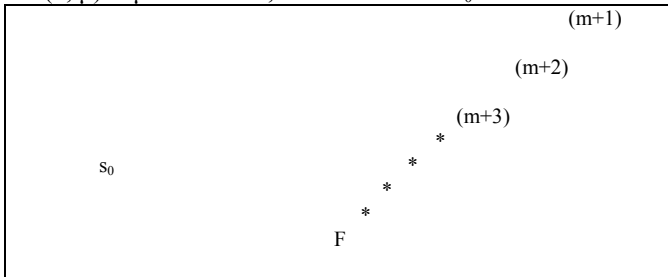
Therefore,

1	2	...	μ_1
$(m+1) \dots (m+\lambda_1-\mu_1)$			
$t_0 = (\mu_1+1)$	$(\mu+2)$...	$(m+\lambda_1-\mu_1+1)$
$(\mu_1+\dots \mu_{l-1}+1)$...	m	
$(f-\lambda_d+1)$...		f

Then 'e' defined by $e = e_{t_0} \times e_{s_0}$ is 'e' is an idempotent in the group algebra of G corresponding to the irreducible $\phi_\lambda \otimes \phi_\mu$.

2.2. Definition:-

The pair (λ, μ) is μ - external if $[\lambda/\mu]$ has no pair of squares in the same row or the same column. If (λ, μ) is μ - extremal, then the tableau t_0 looks like.



Any lattice permutation of length $2k$ and shape η constitutes a littlewood - Richardson filling of $[\lambda/\mu]$. So for all η we have,

$$\text{Thus, } m(\mu, \lambda) = \sum_{\eta \text{ even}} g_{\lambda, \mu, \eta} = f_\eta = 1.3 \dots (2k-1).$$

Hence the multiplicity $m(\mu, \lambda)$ equals the number of 1-factors on $2k$ points.

2.3. Note:-

For any pair (λ, μ) we have $g_{\lambda, \mu, \eta} \leq f_\eta$
 In general $m(\mu, \lambda) \leq 1.3 \dots (2k-1)$.
 Equality is achieved if and only if (λ, μ) is μ -extremal.

2.4. Definition:

Let Δ be a 1- factor with $2k$ points. Define the (m, k) partial 1- factor V_Δ as follows:

- V_Δ has free points $1, 2, \dots, m$. The free point j has label j .
- For every edge (u, v) of Δ we have the edge $(m+u, m+v)$ of V_Δ

The following lemma will not only show that the eV_Δ linearly independent, it will also greatly streamline our computation. This result is difficult to prove in the case of general pairs (λ, μ) .

2.5. Lemma:

Let (λ, μ) be μ -extremal and define t_0, s_0 as above. Let γ, σ, γ' and σ' be in $C_{t_0}, R_{t_0}, C_{s_0}$ and R_{s_0} , respectively (so, $\text{sgn}(\gamma) = \text{sgn}(\gamma')$ and $\text{sgn}(\sigma) = \text{sgn}(\sigma')$) is one of the terms occurring in the idempotent $e = e_{t_0} \times e_{s_0}$. Suppose that

$$(\gamma\sigma, \gamma'\sigma') V_\Delta = V_{\Delta_1}, \text{ where } \Delta \text{ and } \Delta_1 \text{ are 1-factors. Then}$$

- $\Delta = \overline{\Delta_1}$,
- γ and σ both fix t_0 / s_0 point wise.
- γ restricted to s_0 equals γ' and σ restricted to s_0 equals σ' .

In particular, $\{eV_\Delta : \Delta \text{ is a 1- factor with } 2k \text{ points}\}$ is a basis for $eV_{m,k}$.

Proof:

Let γ, σ' acts on an m,k Partial 1-factor by changing the labels on the free points by (γ', σ') .

Since the free points of both Δ and Δ_1 , are $1, 2, \dots, m$, it follow that $\gamma\sigma$ Preserves the sets $\{1, 2, \dots, m\}$ and $\{m+1, \dots, f\}$.

In t_0 , each square $m+u (u=1, 2, \dots, 2k)$ is at the right-hand end of the row containing it and at the bottom of the column containing it.

So σ moves the point $m+u$ weakly to the left. Since the image of $m+u$ under $\gamma\sigma$ is in the set $\{m+1, \dots, f\}$, the permutation γ must then move $\sigma(m+u)$ down to the bottom of the column it occupies.

Thus, $(\gamma\sigma)(m+u) = m+v$, where $v \geq u$.

It follows that $\gamma\sigma$ fixes the set $\{m+1, \dots, f\}$ pointwise.

Now, consider $\gamma\sigma \times \gamma' \sigma'$ on s_0 . The point j is moved by $(\gamma\sigma, \gamma' \sigma')$ to $\gamma\sigma(j)$ and its label is changed to $(\gamma' \sigma')j$.

Since $(\gamma\sigma, \gamma' \sigma') V_\Delta = V_{\Delta_1}$, we have $(\gamma\sigma)j = (\gamma' \sigma')j$ for all j .

Thus, $\gamma\sigma = \gamma' \sigma'^{-1}$, so $\gamma = \gamma'$ and $\sigma = \sigma'^{-1}$ where these last three equalities refer to $\gamma\sigma, \gamma$ and σ restricted to the points of s_0 .

Suppose $\sum a_\Delta eV_\Delta = 0$. Then $\sum a_\Delta V_\Delta = 0$, and so all $a_\Delta = 0$, as the V_Δ are linearly independent.

Thus the set $\{eV_\Delta\}$ is a basis.

2.6. Definition:

Let $(a_i, b_i) (i=1, 2, \dots, 2k)$ be the co-ordinates of the squares of $[\lambda/\mu]$. For each i define sets $C^{(i)} \subseteq C_{t_0}$ and $R^{(i)} \subseteq R_{t_0}$ as follows:

- $C^{(i)}$ contains the identity permutation as well as the (a_{i-1}) involutions $\gamma_{i,j}$ which exchange the elements of t_0 in squares (a_i, b_i) and (j, b_i)
- $R^{(i)}$ contains the identity permutation as well as the (b_{i-1}) involutions $\gamma_{i,j}$ which exchange the elements of t_0 in squares (a_i, b_i) and (a_i, j)

Let C be the set of all products $\gamma^{(1)} \dots \gamma^{(2k)}$, where $\gamma^{(i)} \in C^{(i)}$, and let R be the set of all products $\sigma^{(1)} \dots \sigma^{(2k)}$ where $\sigma^{(i)} \in R^{(i)}$

C and R are subsets of C_{t_0} and R_{t_0} of sizes

$$|C| = a_1 a_2 \dots a_{2k}, \quad |R| = b_1 b_2 \dots b_{2k}$$

Hanlon and Wales algorithm:

Let G be a finite group with irreducible representation Φ_1, \dots, Φ_c . Let Φ be a representation of G on a complex vector space V which decomposes into irreducible as $\Phi = \sum m_i \Phi_i; i: 1$ to c

Let Z be a linear transformation of V which commutes with the action of G . Then Z is similar to a matrix which is a direct sum over i of matrices Z_i , where Z_i is an $m_i \times m_i$ matrix repeated in the direct sum $\text{deg}(\Phi_i)$ times. Moreover, Z_i can be computed as follows:

Step 1 : Choose a complete set of Primitive orthogonal idempotents

$$e_v^{(u)} : 1 \leq u \leq c, 1 \leq v \leq \text{deg}(\Phi_u) \text{ in the group algebra } CG.$$

Step 2: Find m_i vectors $v_1, \dots, v_{m_i} \in V$ such that $\Phi(e_i^{(u)}) v_{mi}$ are linearly independent.

Step 3:-

Let $v_1^{(i)}$ be the subspace of V spanned by $\Phi(e_1^{(i)}) v_1 \dots \Phi(e_1^{(i)}) v_{m_i}$. The space $v_1^{(i)}$ is Z -invariant and Z_i is the restriction of Z to $v_1^{(i)}$.

The above algorithm will compute the $V_{\Delta_2}, V_{\Delta_1}$ entry in $Z_{\lambda,\mu}(x)$ as a sum of terms of the form $\tau = \{(\gamma\sigma, \gamma'\sigma') V_{\Delta_2}, V_{\Delta_1}\}$ where $\gamma \in C, \sigma \in R, \gamma' \in C_{s_0}, \sigma' \in R_{s_0}$. For a fixed pair $(r, \sigma) \in C \times R$ there is at most one pair $(r', \sigma') \in C_{s_0} \times R_{s_0}$ for which τ is nonzero.

We next write down a method for computing $\pi = Y' \sigma'$ given $(Y, \sigma) V_{\Delta_2}$, and V_{Δ_1} . In the description below we will assume that the input is $\delta_1 = Y \sigma V_{\Delta_2}$ and $\delta_2 = V_{\Delta_1}$.

2.7. Definition:

Let δ_1 and δ_2 be (m, k) partial 1- factors. Define an element $\pi(\delta_1, \delta_2)$ in the group algebra CS_m according to the following algorithm.

For each i in the set $\{1, 2, \dots, m\}$ find the unique path in $\delta_1 \cup \delta_2$ which begins at the free point of δ_1 labelled i and ends at some other free point y . If y is a free point of δ_1 , then $\pi(\delta_1, \delta_2) = 0$ and algorithm stops. Otherwise, y is a free point of δ_2 . Let $\pi(\delta_1, \delta_2)(i)$ be the label on y .

When this algorithm finishes, we will have either, $\pi(\delta_1, \delta_2) = 0$ or else $\pi(\delta_1, \delta_2) \in S_m$. For δ_1, δ_2 both (m, k) partial 1-factors and r a standard young tableau of size m , define $\Gamma_Y(\delta_1, \delta_2)$ by

$$\Gamma_Y(\delta_1, \delta_2) = \begin{cases} 0 & \text{if } \pi(\delta_1, \delta_2) = 0 \text{ the coefficient of } \pi(\delta_1, \delta_2) \\ & \text{in the young symmetrizer} \\ e_r & \text{if } \pi(\delta_1, \delta_2) \in S_m \end{cases}$$

2.8. Lemma:

Let $Y = Y^{(1)} \dots Y^{(2k)}$ be in C and $\sigma = \sigma^{(1)} \dots \sigma^{(2k)}$ are not identity. Then $\Gamma_{s_0}(Y \sigma V_{\Delta_2}, V_{\Delta_1}) = 0$

Proof:-

Fix i such that $Y^{(i)} = (u, b_i)$ with $u < a_i$ and $\sigma^{(i)} = (a_i, v)$ with $v < b_i$.

Let α and β be the labels in the squares (u, b_i) and (a_i, v) of t_0 .

The row permutation σ moves the label β to the corner square (a_i, b_i) .

Then the column permutation Y moves the label to the square (u, b_i) .

So in $Y \sigma V_{\Delta_2} \cup V_{\Delta_1}$, the path beginning at the free point labeled β in $Y \sigma V_{\Delta_2}$ has length 0 and ends at the same point of V_{Δ_1} which is a free point labeled α .

So, $\pi(Y \sigma V_{\Delta_2}, V_{\Delta_1})(\beta) = \alpha$.

But the corner square (a_i, b_i) does not exist in s_0 , so $\pi(Y \sigma V_{\Delta_2}, V_{\Delta_2})$ moves β from position (a_i, v) to (u, b_i) where $b_i > \mu a_i$.

It is easy to see that such a permutation cannot be written in the form $Y \sigma$ where

$$Y \in C_{s_0} \text{ and } \sigma \in R_{s_0} \quad \text{---}$$

So, $\Gamma_{s_0}(Y \sigma V_{\Delta_2}, V_{\Delta_1}) = 0$.

This completes the proof.

2.9. Note:

Let S denote the set of Pairs $(Y \sigma)$ with $Y = Y^{(1)} \dots Y^{(2k)} \in C$ and $\sigma = \sigma^{(1)} \dots \sigma^{(2k)} \in R$ Such that $\sigma^{(1)}$ is the identity wherever $Y^{(i)}$ is not the identity.

The size of S is $|S| = \pi(ai+bi-1)$.

2.10. Theorem:

The following algorithm compute the Δ_i, Δ_j entry in $Z_{\lambda,\mu}(x)$. Algorithm for each pair $(\gamma, \sigma) \in \delta$.

1. Compute $\Gamma_{s_0}(\gamma \sigma V_{\Delta_j}, V_{\Delta_i})$.
2. Compute the number of cycles N in $\gamma \sigma V_{\Delta_j} U V_{\Delta_i}$.
3. Add $\text{Sgn}(\gamma) \Gamma_{s_0}(\gamma \sigma V_{\Delta_j}, V_{\Delta_i}) x^N$ to the current value of $Z_{\lambda,\mu}(x)$.

Before proving this algorithm consider the case $\lambda = (6, 5, 4, 3, 2, 1)$ and $\mu = (5, 4, 3, 2, 1)$.

The size of original matrix $Z_{m,\mu}(x)$ is a whopping $(21)!/48$. The submatrix $Z_{\lambda,\mu}(x)$ is 15×15 . The six squares of $[\gamma/\mu]$ have

co-ordinates $(1,6), (2,5), (3,4), (4,3), (5,2)$ and $(6,1)$, so the size of S is 6^6 .

Thus each entry of $Z_{\lambda,\mu}(x)$ is computed with 6^6 passes through the main loop of the algorithm in above theorem.

In practice, this matrix $Z_{\lambda,\mu}(x)$ was computed in about one hour of CPU time on a CRAY-2.

In general, we must perform the main loop in the above algorithm $\pi(a_i+b_i-1)$ times. This main loop is carried out in $O((f+\sum a_j(a_j+1))\text{steps})$.

So, the above Theorem gives a method to compute each entry of $Z_{\lambda,\mu}(x)$ in $O(\pi(a_i+b_i-1)(f+\sum a_j(a_j+1))\text{steps})$.

Proof:

Let $e = c_{s_0} \Gamma_{s_0}$ be the young symmetrizer indexed by s_0 .

According to Theorem, Let G be a finite group with irreducible representation Φ_1, \dots, Φ_c . Let Φ be a representation of G on a complex vector space V which decomposes into irreducible as $\Phi = \sum m_i \Phi_i, i: 1$ to c

Let Z be a linear transformation of V which commutes with the action of G . Then Z is similar to a matrix which is a direct sum over i of matrices Z_i , where Z_i is an $m_i \times m_i$ matrix repeated in the direct sum $\text{deg}(\Phi_i)$ times. Moreover, Z_i can be computed as follows:

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Step 3:-

Let $v_1^{(i)}$ be the subspace of V spanned by $\Phi(e_1^{(i)}) v_1 \dots \Phi(e_1^{(i)}) v_{m_i}$. The space $v_1^{(i)}$ is Z -invariant and Z_i is the restriction of Z to $v_1^{(i)}$.

the matrix $Z_{m,k}(x)$ preserves the subspace $\{eV_\Delta : \Delta \text{ is a 1-factor of size } 2k\}$. By Lemma, Let (λ, μ) be μ -extremal and define t_0, s_0 as above. Let γ, σ, γ' and σ' be in $C_{t_0} \times R_{s_0}$ and R_{s_0} , respectively (so, $\text{sgn}(\gamma) \text{sgn}(\gamma') (\gamma\sigma, \gamma'\sigma')$ is one of the terms occurring in the idempotent $e = e_{t_0} \times e_{s_0}$). Suppose that

1. $(\gamma\sigma, \gamma'\sigma') V_\Delta = V_{\Delta_1}$, where Δ and Δ_1 are 1-factors. Then
2. $\Delta = \Delta_1$,
3. γ and σ both fix t_0 / s_0 point wise.
4. γ restricted to s_0 equals γ' and σ restricted to s_0 equals σ' .

In particular, $\{eV_\Delta : \Delta \text{ is a 1-factor with } 2k \text{ points}\}$ is a basis for $eV_{m,k}$.

the co-efficient of v_{Δ_i} in eV_{Δ_j} is 0 for $i \neq j$ and is $|R_{s_0}| |C_{s_0}|$ for $i=j$.

so the i,j entry of $Z_{\lambda,\mu}(x)$ is $(1/|R_{s_0}| |C_{s_0}|)$ times the coefficient of v_{Δ_i} in $Z_{\lambda,\mu}(x)(ev_{\Delta_j})$.

Thus

$$\begin{aligned} (Z_{\lambda,\mu}(x))_{\Delta_i,\Delta_j} &= \frac{1}{|R_{s_0}| |C_{s_0}|} (ev_{\Delta_j}, v_{\Delta_i}) \\ &= \frac{1}{|R_{s_0}| |C_{s_0}|} \sum_{\substack{\gamma \in C_{t_0} \\ \sigma \in R_{t_0}}} \text{Sgn}(\gamma) \\ &= \sum_{\substack{\gamma' \in C_{s_0} \\ \sigma' \in R_{s_0}}} \text{Sgn}(\gamma') \{(\gamma\sigma, \gamma'\sigma') v_{\Delta_i}\} \end{aligned}$$

$$= \sum_{\gamma \in C} \sum_{\sigma \in R} \text{Sgn}(\gamma) \Gamma_{s_0}(\gamma\sigma v_{\Delta_j}, v_{\Delta_i})(\gamma\sigma v_{\Delta_j}, v_{\Delta_i}).$$

This equality follows from the definition Γ_{s_0} . we have $(Z_{\lambda,\mu}(x))_{\Delta_i,\Delta_j} = \sum_{(\gamma, \sigma) \in S} \text{Sgn}(\gamma) \Gamma_{s_0}(\gamma\sigma v_{\Delta_j}, v_{\Delta_i})(\gamma\sigma v_{\Delta_j}, v_{\Delta_i})$.

This completes the proof.

CONCLUSION:

I have tried to give a brief sketch of some of the main ideas underlying the dynamically growing field of Brauer Centralizer Algebra. It is the natural Convergence of ideas from many areas of mathematics such as algebra, combinatorics, with those from computers science, such as algorithms, data structures. I feel confident that the current trend of studying Brauer Algebra will continue to suggest new classes of problems which are can continue for further enrichment of his knowledge.

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